

## **ESPAStar™**

# Flexible, Affordable Access to Space

Northrop Grumman's ESPAStar platform provides a modular, cost-effective, and highly capable infrastructure resource for hosting technology development and operational payloads. The ESPAStar platform uses a customized EELV Secondary Payload Adapter (ESPA) ring as part of its structure and is capable of being launched aboard any launch vehicle that meets the Evolved Expendable Launch Vehicle (EELV) standard interface specification.

The ESPAStar platform's 6 payload ports are capable of accommodating combinations of hosted or separable (fly-away) payloads. The payload interface at each port has been standardized, allowing for hosted and separable payload interchangeability, late payload integration, and manifest changes. The ESPAStar platform leverages the available mass margin from any EELV launch to provide an affordable path to space for payloads. The platform is optimized for GEO missions, but is adaptable for LEO and MEO missions.

### **FACTS AT A GLANCE**

- Accommodates combinations of hosted or separable payloads on six ports
- > 1,920 kg payload (>320 kg per port)
- Multi-year mission life
- 1.6 Mbps downlink, AFSCN-compatible, Type 1 encryption
- Low jitter
- ≥400 m/s delta-V, any direction
- EELV SIS Rev B compliant
- Comprehensive payload power and data interfaces





### **ESPAStar™**

### **SPECIFICATIONS**

**SPACECRAFT** 

Orbit: Optimized for GEO, adaptable for LEO

and MEO missions
One to three years,

Targeted Mission

Duration:

Dry Mass (no P/Ls):

single string 430-470 kg (orbit dependent)

310 kg

Dimensions (no P/Ls):

157.5 cm dia x 61 cm ht. (62" dia. x 24" ht.)

Fuel Capacity\*:

Payload Mass:

> 1,920 kg (> 320 kg per port)

Total Power (BOL):

1,200 W via four-panel solar array

Payload Peak Power:

Tailorable based on mission profile

96 A-hr Li-ion

Battery:

Downlink Rate:

256 kbps/1.6 Mbps via AFSCN higher downlink rates avail-

able upon request

Uplink Rate:

2.0 kbps via AFSC higher uplink rates available upon

request

Payload Data Storage:

36 Gbytes non-TMR, non-volatile, 500 kbytes/day/ payload SOH

Attitude Knowledge<sup>a</sup>:

< 10 µrad (1<sub>0</sub>)

Attitude Control $^{\beta}$ :

< 50 µrad (1ơ) via 3-Axis RWA control

Jitter at Payload

Interface:

< 20 µrad, (10), >0.1 Hz

Slew Rate:

≥ 0.5 deg/sec

Position Control:

12x .09 N and 4x22 N REAs, 6 DoF control

Position Knowledge:

< 25 m (lo), < 5 m

typical

Avionics:

IAU, BRE440 processor, Virtex 5 FPGA, 40 GB memory

## $^{\star}\!=\!$ Fuel capacity can be increased by adding auxiliary propulsion tanks at payload ports

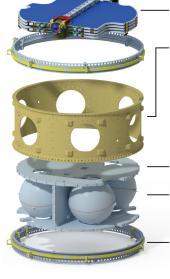
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#### MISSION SERVICES

- Mission Analysis
- Payload Integration
- Testing and Verification
- Launch Vehicle Integration
- Launch Operations
- Mission Operation
- Safety & Mission Assurance

### **ESPAStar PLATFORM**



4 panel solar array (stowed)

Six-port ESPA ring with 4-point hard mounts per port

Internal forward deck, aft deck, bulkhead structure aluminum honeycomb

Hydrazine propulsion module

RUAG clampband, top and bottom LV IF



### FOR MORE INFORMATION

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 $<sup>^{\</sup>rm Cl}$  = Assumes additional contributions to attitude knowledge error are removed by adding additional star tracker head and/or payload data

 $<sup>\</sup>beta = \text{Assumes} < \text{10} \; \mu \text{rad} \; (\text{1}\sigma) \; \text{attitude knowledge error}$